

One Model – Two Approaches Lessons Learned from Implementing a Model Twice

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A Model of Routes and Rumors (Model World)



Entries

Cities resources $\in [0, 1]$ control $\in [0, 1]$

Transport Links friction $\in [0, 1]$ distance $\in [0, 1]$

Exits



A Model of Routes and Rumors (Migrant Behavior)

Agents start at an **entry**, and try to find the way to any **exit**, acting on **limited information**.

Information: (subject, value, trust)

Behavior options:

- Explore the current cities
- Make contacts
- Exchange information with contacts
- Move to a neighboring cities



Two Approaches

Rostocl

Approach 1: Julia

- Modern (somewhat) general purpose language
- Designed for scientific computing

Approach 2: ML3

- Domain-specific modeling language for agent-based demographic models
- Agents interacting in dynamic networks
- Stochastic rules in continuous time



Implementation 1: Julia

Discrete time steps.

Rostock

At each time steps migrants might ...

- Stay to explore, make contacts
- Move to a neighboring city
- ... in addition to always exchanging information



Rostock

Implementation 2: ML3

Competing risk in continuous time.

All behavior options are "processes" that happen in parallel. Decision between them stochastically via the rate.

```
Migrant
eqo.capital >= 0 && !eqo.in_transit
@ eqo.move_rate()
-> eqo.in_transit := true
   eqo.destination := eqo.decide_destination()
   eqo.capital -= eqo.move_cost(eqo.destination)
```



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A Comparison

Separation of Model and Simulation Logic

Why: Clearer model logic and reusable simulation logic.

Julia: no separation

```
function step_agent!(agent, model, par)
if decide_stay(agent, par) # model logic
step_agent_stay!(agent, model.world, par)
else
step_agent_move!(agent, model.world, par)
end
step_agent_info!(agent, model, par)
...
end
```

ML3: complete separation



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A Comparison

Handling Knowledge

Why: It is difficult.

Very similar in both implementations.

```
Information(
   quality : real,
   resources : real,
   quality_trust : real,
   resources_trust : real
)
```

```
subject:Location[1]<->[n]Information:information
knowledge:Information[n]<->[1]Migrant:owner
```

```
Migrant.knowledge_about(?loc : Location) : Information :=
    ego.knowledge.filter(alter.subject = ?loc).only()
```



A Comparison

Simulation Infrastructure

Why: We need to experiment with the model.

Julia:

 Ad-hoc solutions for observation, parameterization, parallelization of runs, storing results, ...

ML3:

 SESSL binding (a DSL for experiment specification)



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A Comparison

Simulation Infrastructure

SESSL:

```
new Experiment with Observation with ParallelExecution with CSVOutput {
  model = "routes_rumors.ml3"
  simulator = NextReactionMethod()
  parallelThreads = -1
  stopTime = 100
  initializeWith(new RoutesRumorsInit())
  scan("speed_expl_stay" <~ range(0,0.1,1), "p_info_contacts" <~ range(0,0.1,1))
  observeAt(stopTime)
  observe("exiting" ~ expressionDistribution(agentType = "Location", filter =
        "ego.type = 'exit'", expression = "ego.migrants.size()"))
  withExperimentResult(writeCSV)
}</pre>
```



A Comparison

Language Infrastructure

Why: It makes life easier.

Julia:

- IDE
- Ample Documentation
- Community of Users
- Debugger
- REPL

ML3:

- rudimentary Editor
- Some papers with models
- If there are problems, ask me



lessons learned

Rostock

- Using a DSML is worth it, if it suits the needs of the model.
- The rule-based approach works well for external events and continuous behavior, less so active decision making.
- While ML3 is already very expressive (compared to DSMLs for other domains), it is not expressive enough (data structures, attributed links).
- \rightarrow An (internal) DSML for modeling decision making with limited information?